

# Using Camera State Transforms for Commuter Network Visualization

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I. Original problem

II. Metric-based mapping and filtering

III. Camera state mapping

# I. Original problem

Gain insight into a commuter network  
in France

Data from INSEE covering several years:  
1975, 1980, 1995, 1999

~32 000 cities and ~3 000 000 links

# Objectives:

Allow geographers to explore migration data.

Locate the largest and smallest flows.

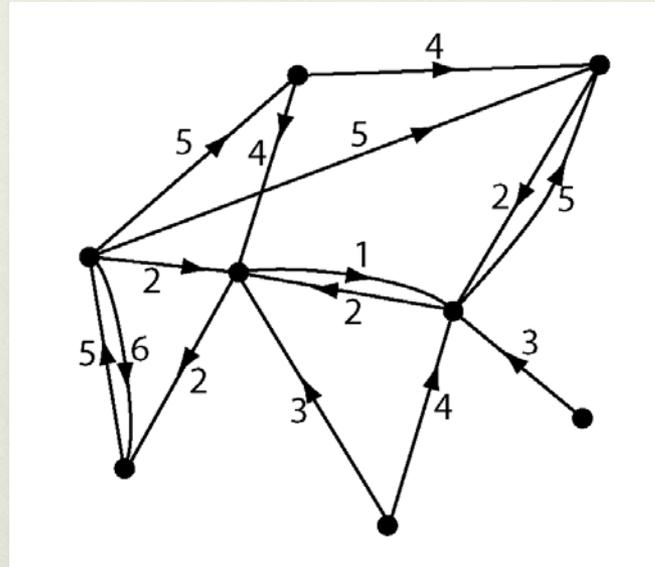
Examine movements.

Compare flows.

Locate origin/destination.

# Our approach:

## Commuter network $\leftrightarrow$ Weighted graph



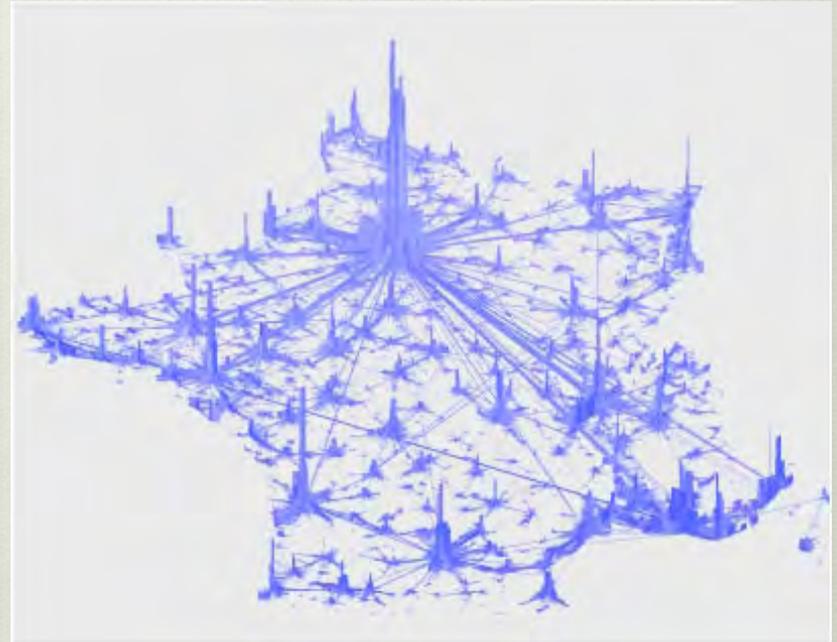
## 2D/3D visualization + metric filtering.

# We use 3D

3D provides more room to show information.

Humans are able to very quickly interpret depth cues, shading, perspective, etc.

3D is convenient for navigation.



## II. Metric-based mapping and filtering

Well-known method to simplify visualization of a graph  $G = (V, E)$ .

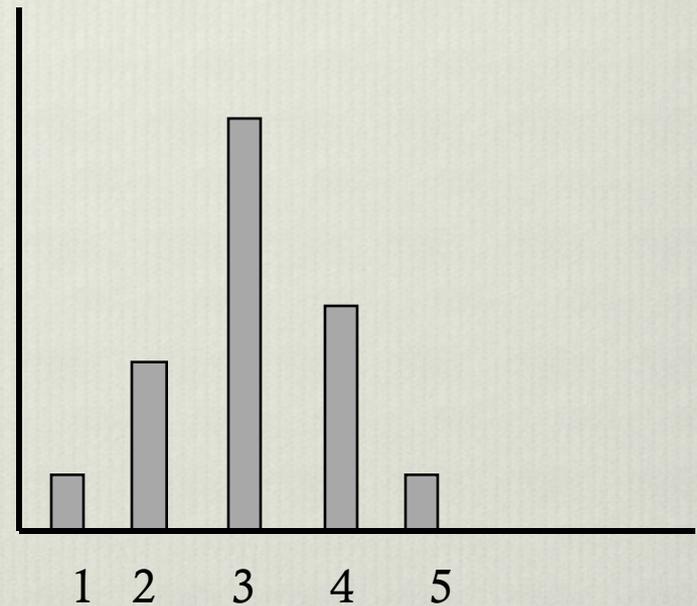
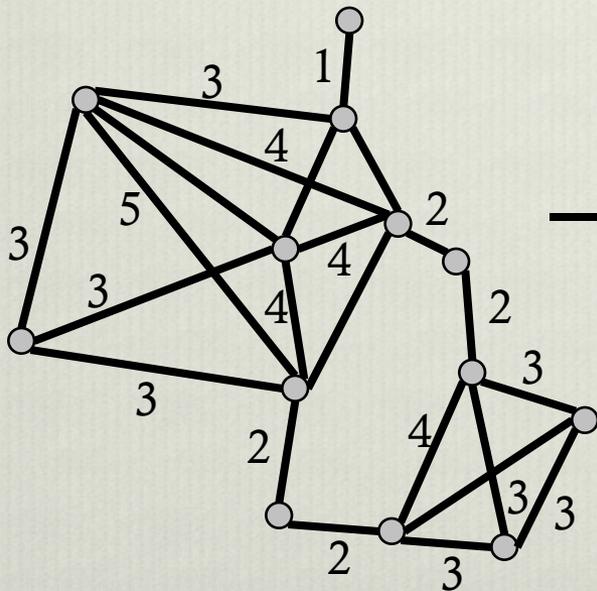
Metric~Weight~Mapping  $f : V \text{ (or } E) \rightarrow \mathcal{R}$

Metric filtering consists of displaying only elements whose weight falls within a certain range (for example, between two specific values).

# Metric-based filtering

Provides a convenient way to achieve graph simplification.

Low-pass filtering : remove from  $G$  edges  $e$  such that  $\Sigma(e) < \tau$ .

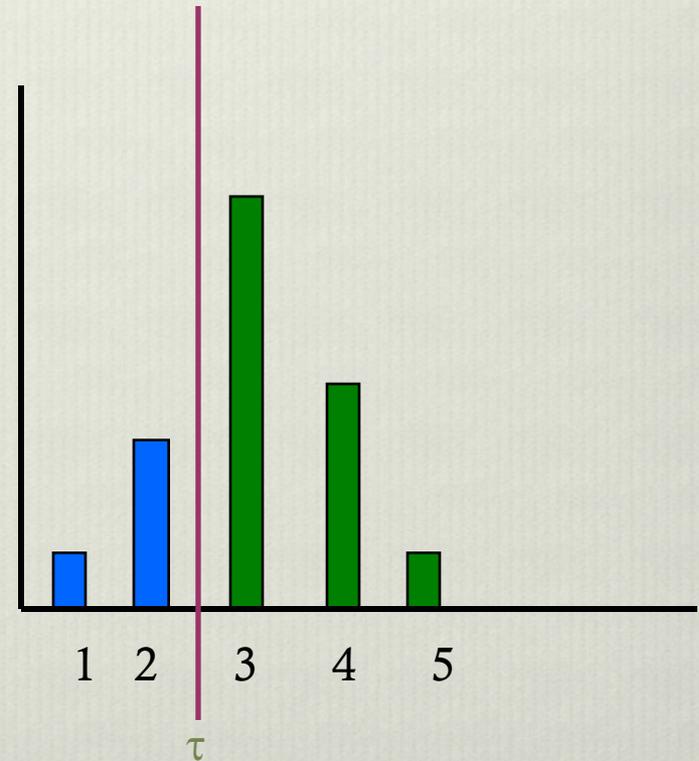
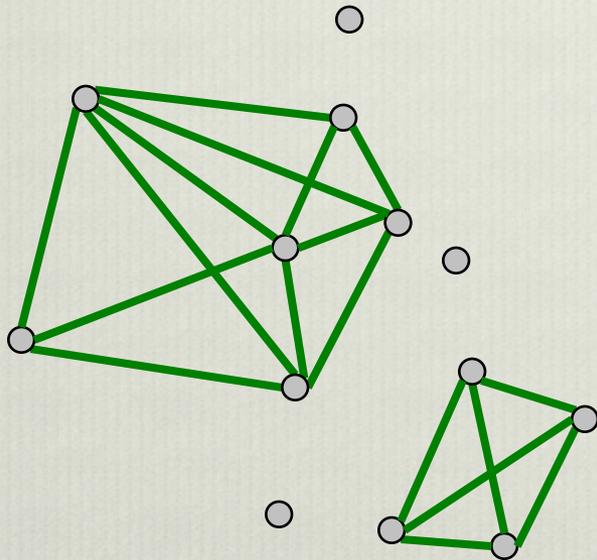




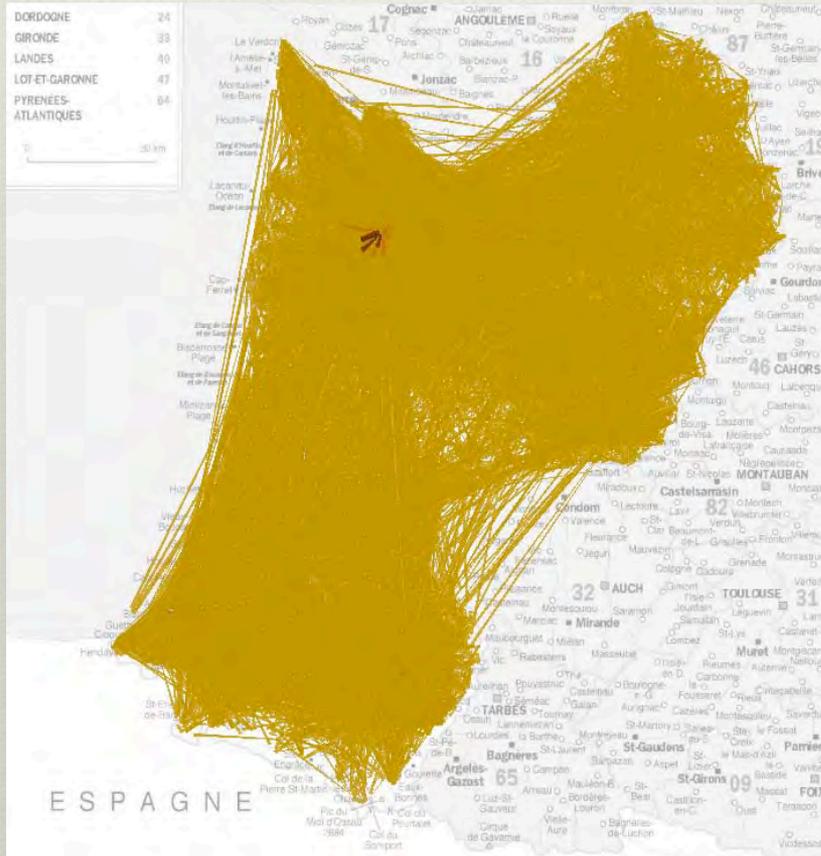
# Metric-based filtering

Provides a convenient way to achieve graph simplification.

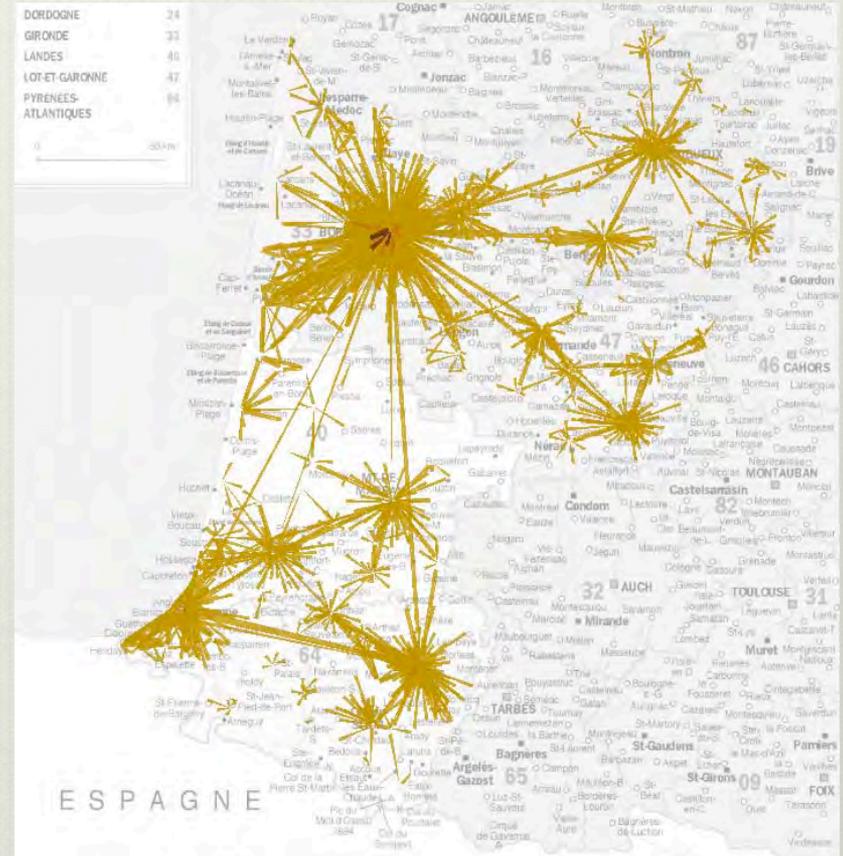
Low-pass filtering : remove from  $G$  edges  $e$  such that  $\Sigma(e) < \tau$ .



# Low-pass filtering removes "noise" in graph layout.



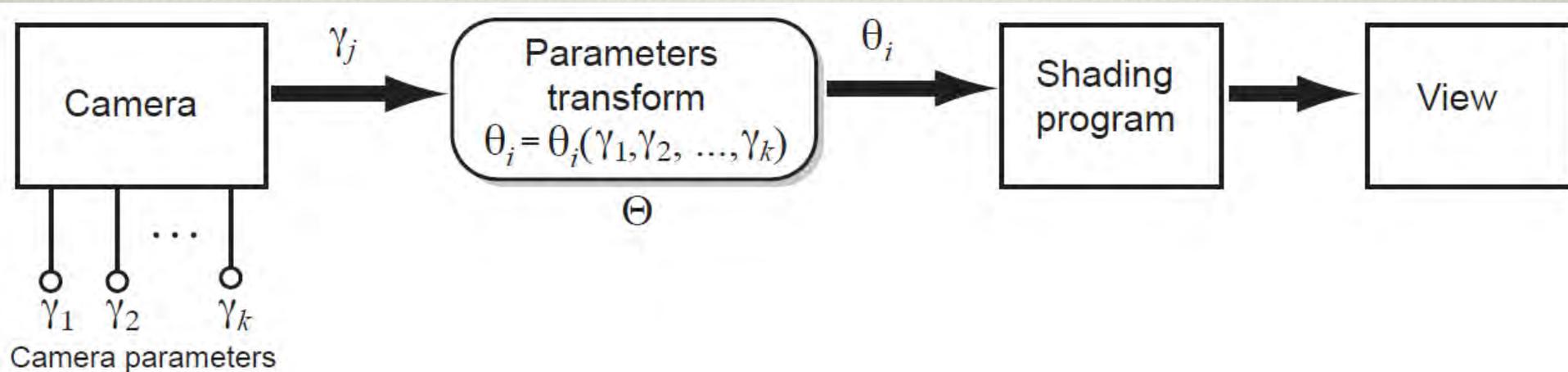
Commuter network for the Aquitaine region of France.



Filtering out links corresponding to 5 workers or less.

# III. Camera state mapping

The idea is to use camera parameters (such as angle of view, distance between camera and point of interest, etc.) to control graphical attributes of objects used to represent the graph (such as link size, color, opacity, morphing parameter, etc).

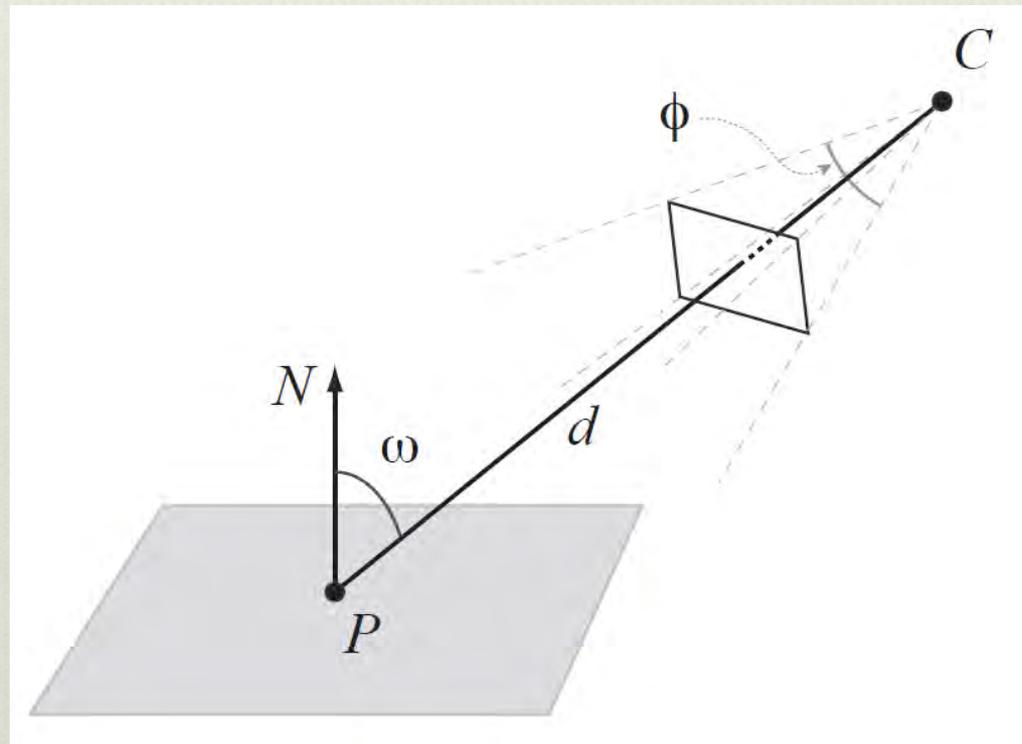


# Typical camera parameters

$\omega$  : angle of view

$d$  : distance between camera and point of interest

$\phi$  : field of view



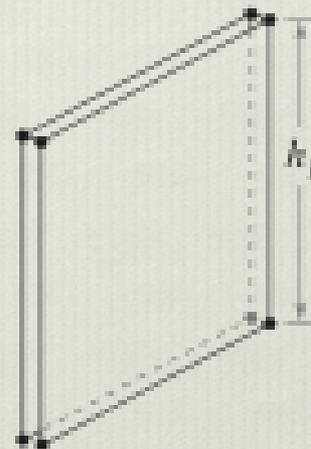
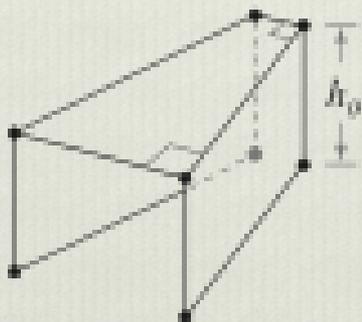
There are multiple graphical attributes (color, opacity, shape, etc.)...

# Example 1 : Morphing links and nodes, in response to changes in camera angle

Nodes:



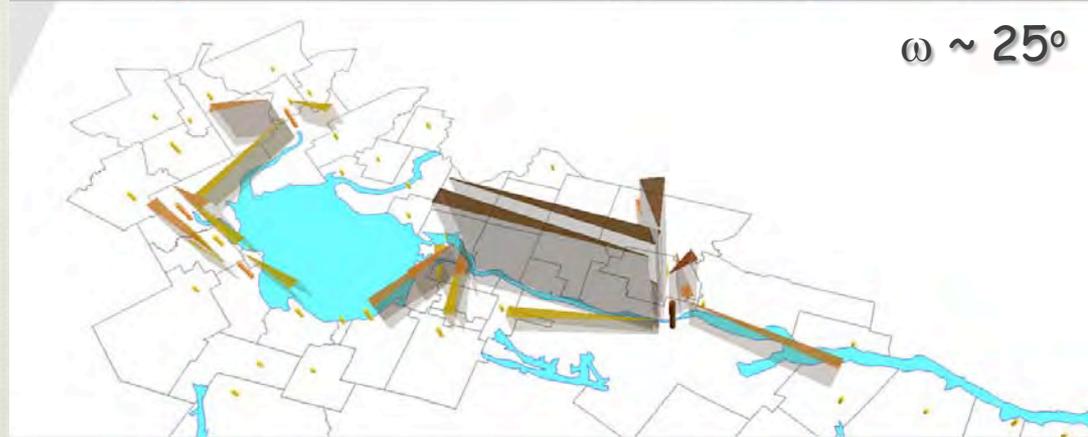
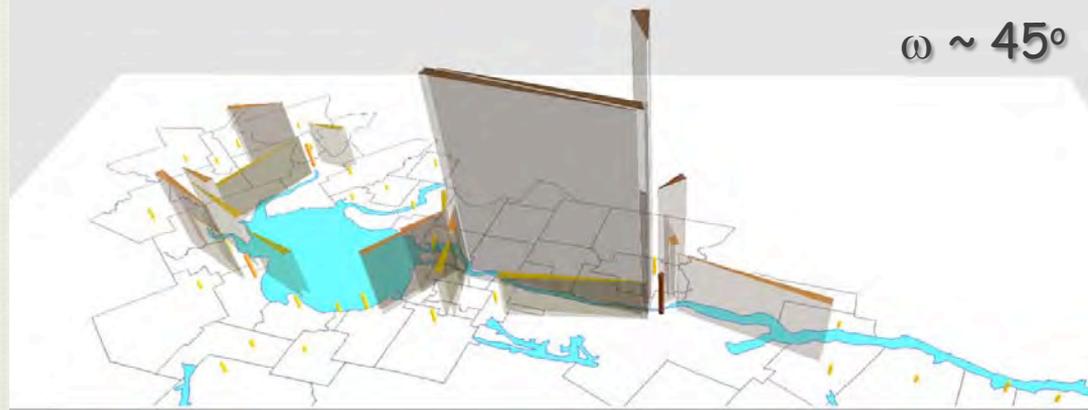
Links:



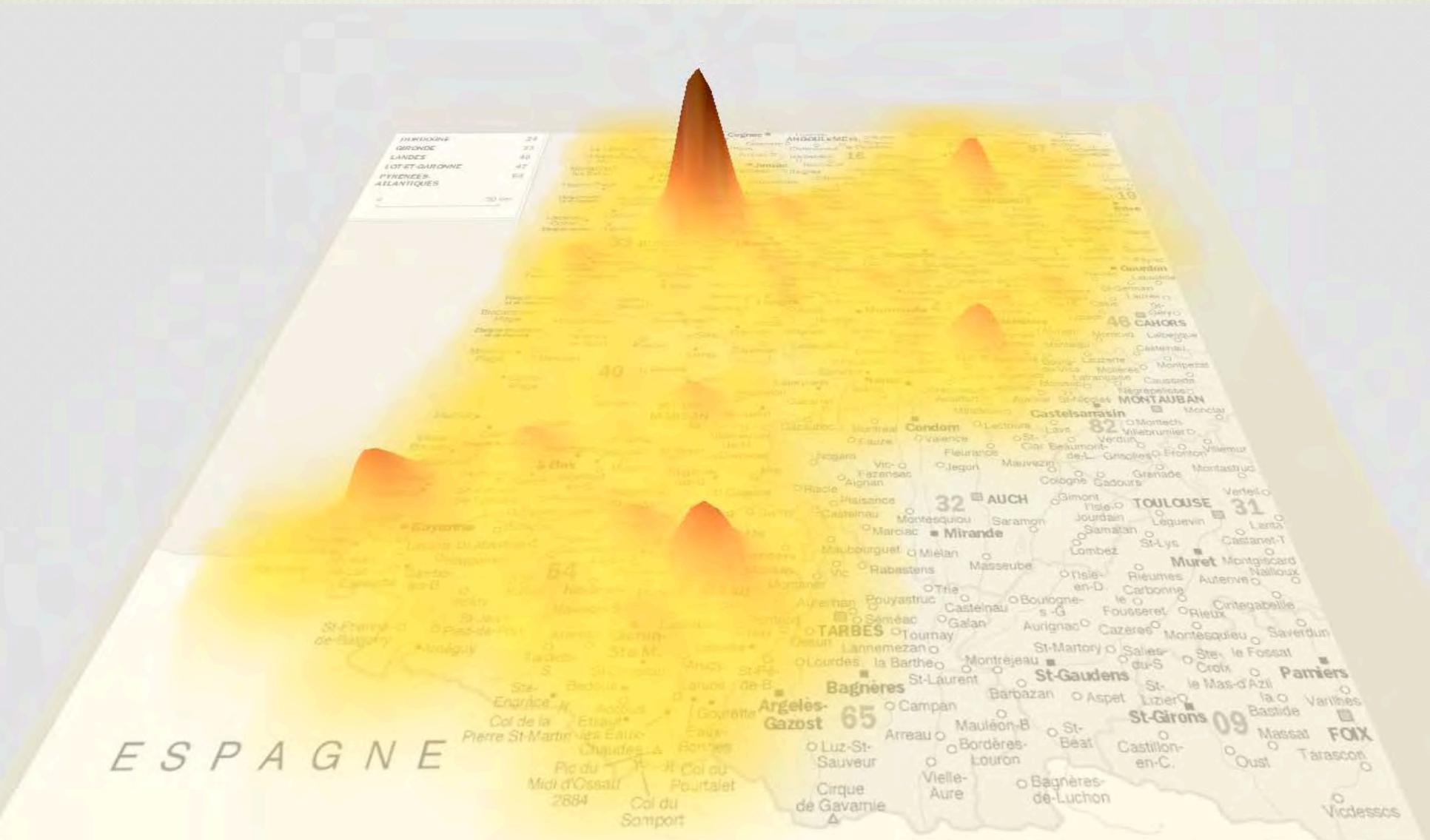
Camera pointing downward ( $\omega \sim 0^\circ$ )

Camera with nearly horizontal orientation ( $\omega \sim 90^\circ$ )

As the camera angle changes, we see a smooth transition from the 3D view to a 2D map.



# Example 2: Surface representation of node metrics



Height and color represent number of workers in towns.

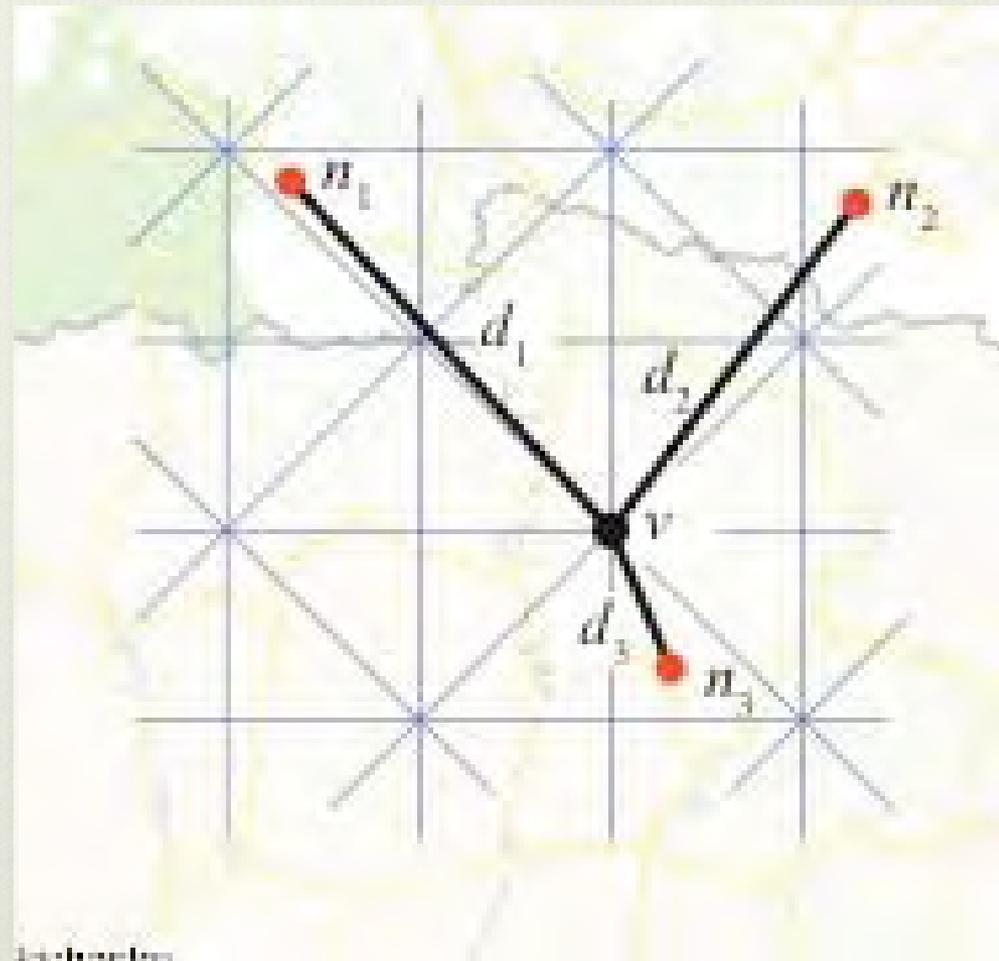
# Mesh calculation

We use a grid.

A priori, the height of each vertice  $v$  in the grid is determined by a metric value of nodes (cities).

For each vertex  $v$ , we sum the nodes' metric values weighted by an inverse exponential depending on distance between the vertex and nodes.

$$h(v) = \sum_i v_i e^{-kd_i}$$



$v_i$  : node  $i$  metric value

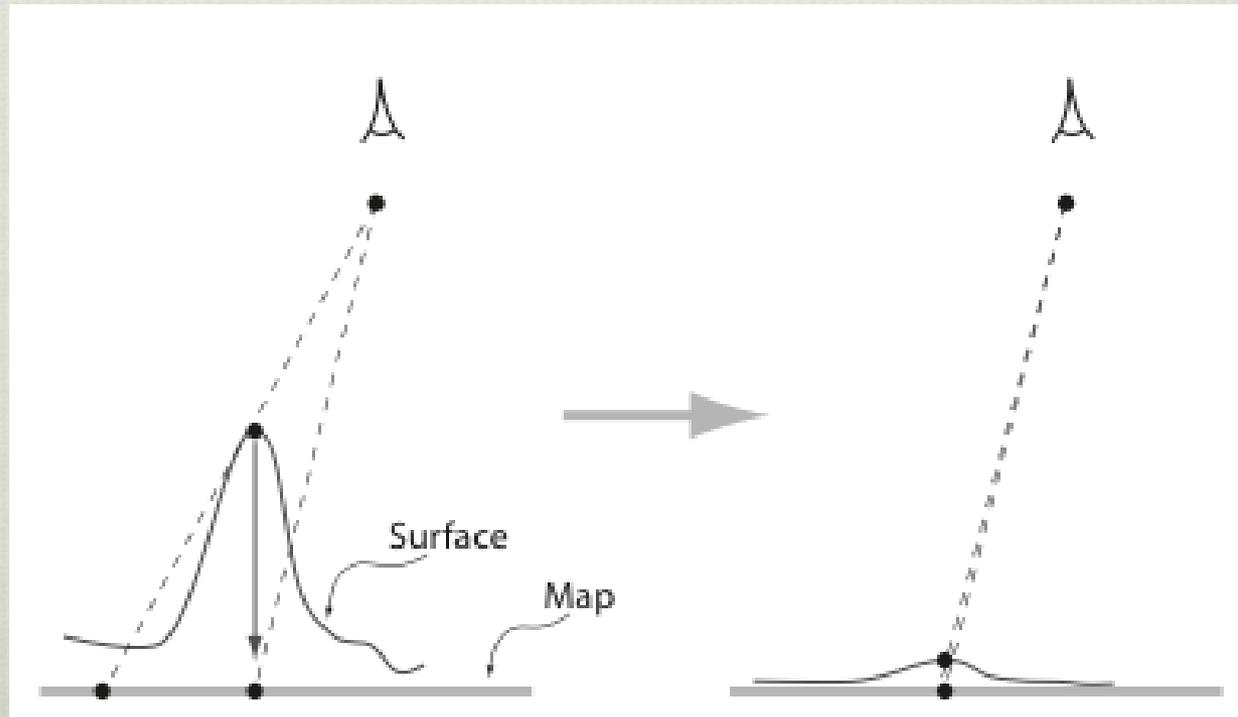
$k$  : calibration constant

$d_i$  : distance between node  $i$  and  $v$

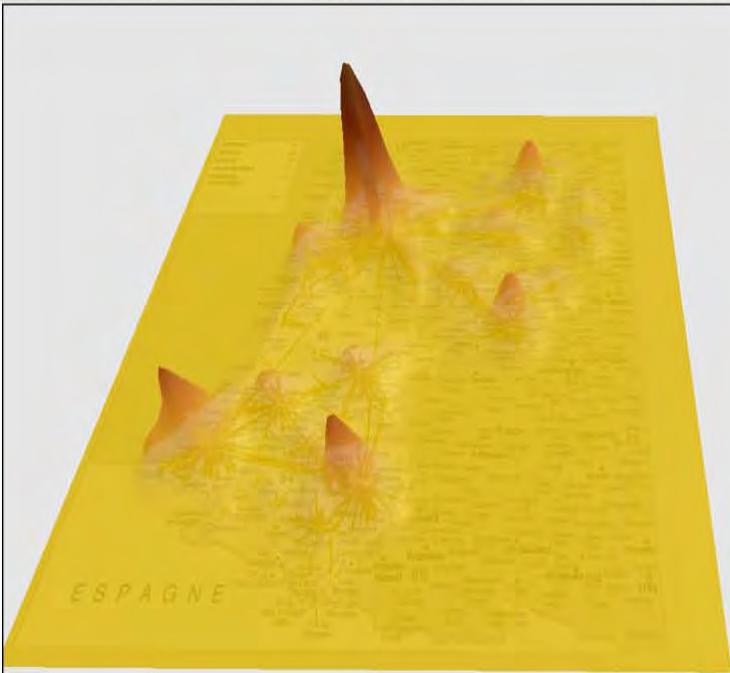
We use morphing, controlled by camera angle of view, to correct parallax.

The morphing acts by flattening the surface as the camera angle approaches the vertical.

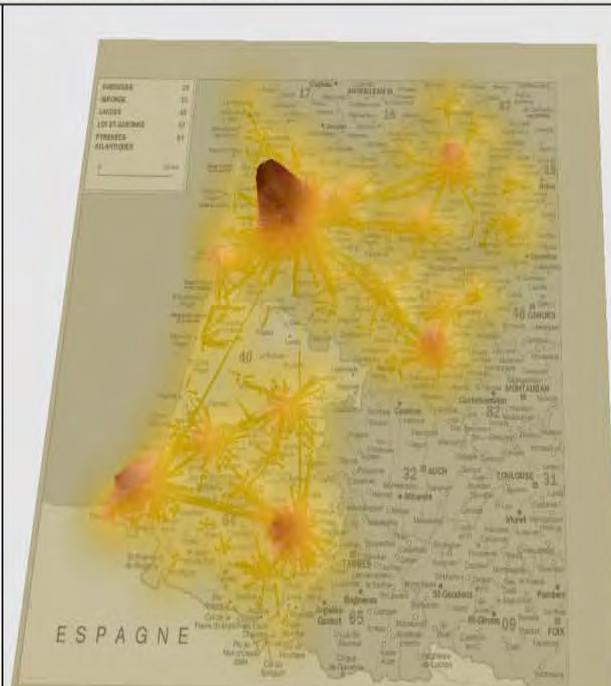
The idea is to prevent the tops of surfaces from being shifted with respect to the underlying map image.



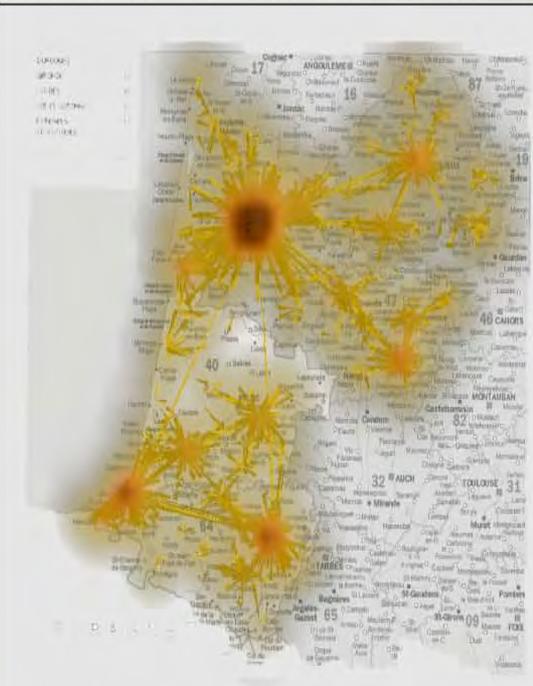
# Using camera state to change opacity whenever 3D view transforms to a 2D map.



(a)



(b)



(c)

Opacity of the surface is determined by angle of view.

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Thank you!