

# Spatial knowledge acquisition with Mobile map, Language and Augmented Reality

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# Background

## Ways2navigate project ...

... investigating the suitability of mobile map, language, and Augmented Reality (AR) for communicating route information to pedestrians

## Three iterative field tests ...

... how these technologies can help to reduce cognitive load during wayfinding

... how these technologies influence the acquisition of spatial knowledge

# Spatial Knowledge Acquisition

Spatial knowledge ...

... essential for wayfinding and other spatial tasks

The effect of navigation systems on spatial knowledge acquisition ...

... people would get lost when navigation systems fail

# Research Goal

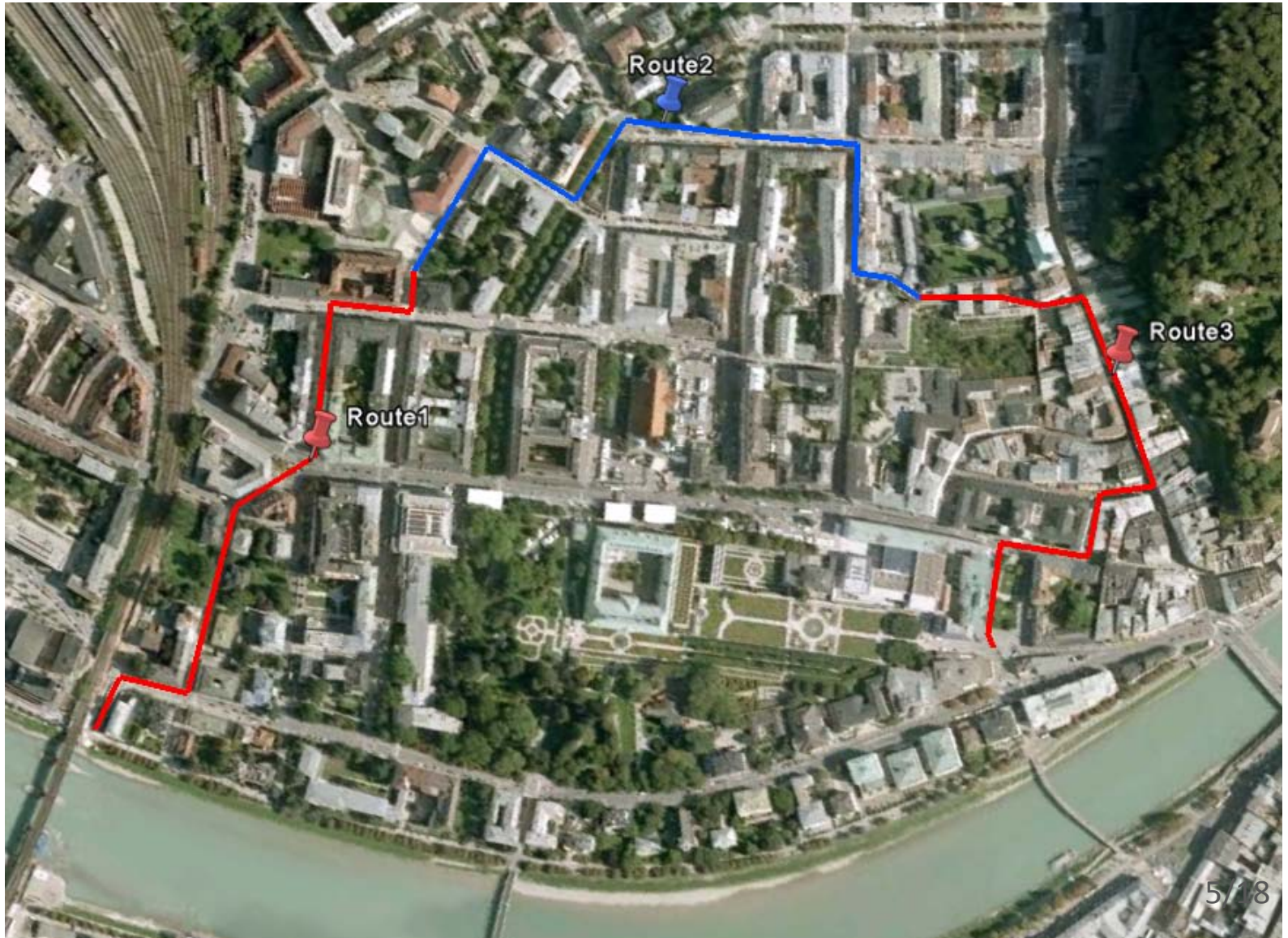
Empirically studying the differences in spatial knowledge acquisition ...

... with different presentation forms:  
**mobile map, language and AR**

... in the context of GPS-based pedestrian navigation

... in an urban environment

# Methodology: Test Route



# Methodology: Test Persons

24 test persons ...

... 13 female, 11 male, age range 22-63 yrs (mean: 40)

... divided into three groups

... within subject design (72 person/sub-route pairs)

# Methodology: Materials



Mobile map



Augmented Reality

Turn right and use  
the cross-walk  
towards the hotel.

Language



# Methodology: Tasks

## Part 1: Route following...

... movement and interaction with the system are logged

## Part 2: Reaching the end of each sub-route ...

... pointing to the start point

... drawing a sketch map

... marking the half of the sub-route



# Data Analysis

Considering **unfamiliarity** ...

... 24 person/sub-route paris (8 mobile map, 8 language, 8 AR)

**Sketch maps** (focusing on topological aspects) ...

... sketched landmarks

... missing/wrong/unnecessary turns

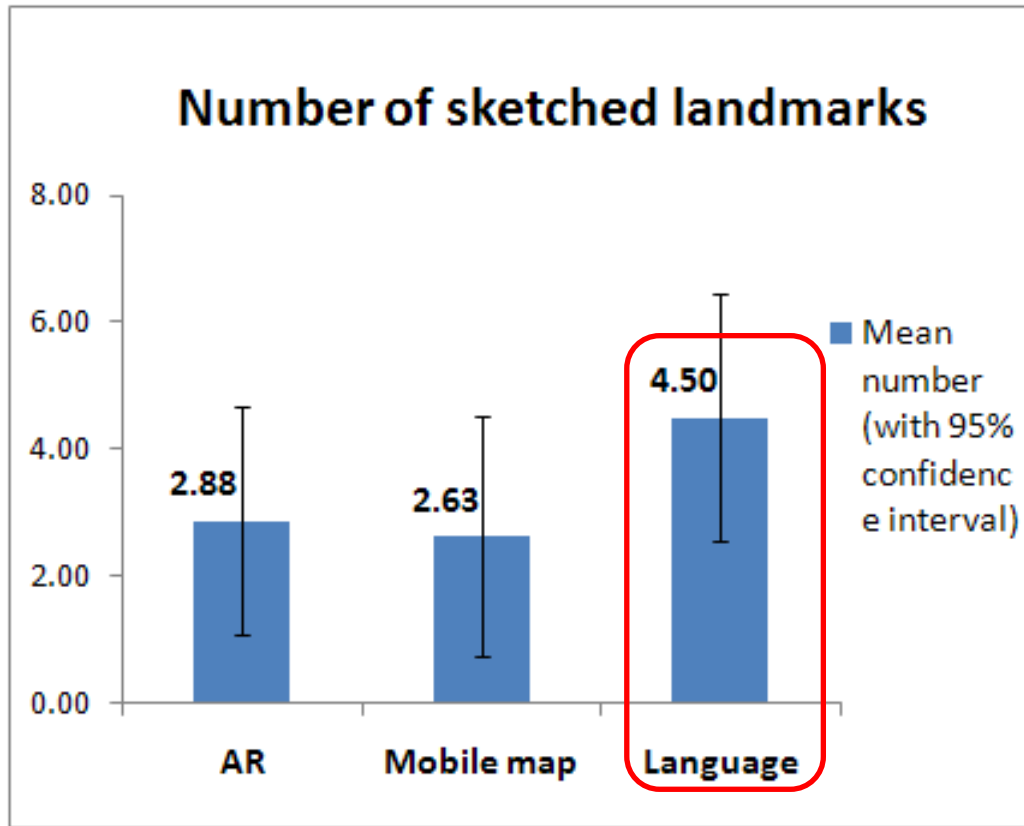
**The pointing task:** sense of direction

... the deviation between correct and pointed direction

**Marking half of the route:** sense of distance

... a grading system

# Results: Number of Sketched Landmarks



**ANOVA (analysis of variance) test:**

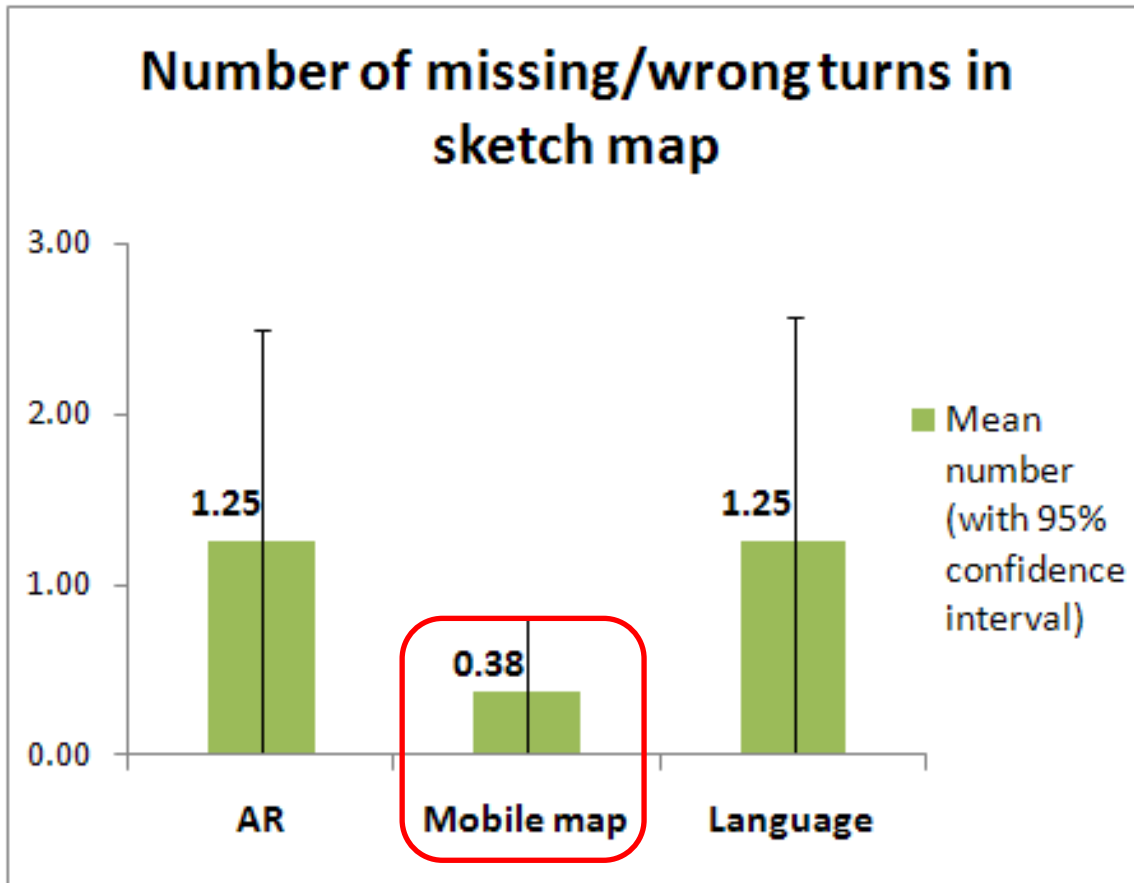
no significant difference in number of sketched landmarks across conditions,  $F(2,21) = 1.63$ ,  $p = 0.22$

... 78% of sketched landmarks in “language” condition are mentioned in the verbal wayfinding instruction

... Landmarks are not explicitly highlighted in “mobile map” and “AR”



# Results: Missing/wrong turns in sketch map

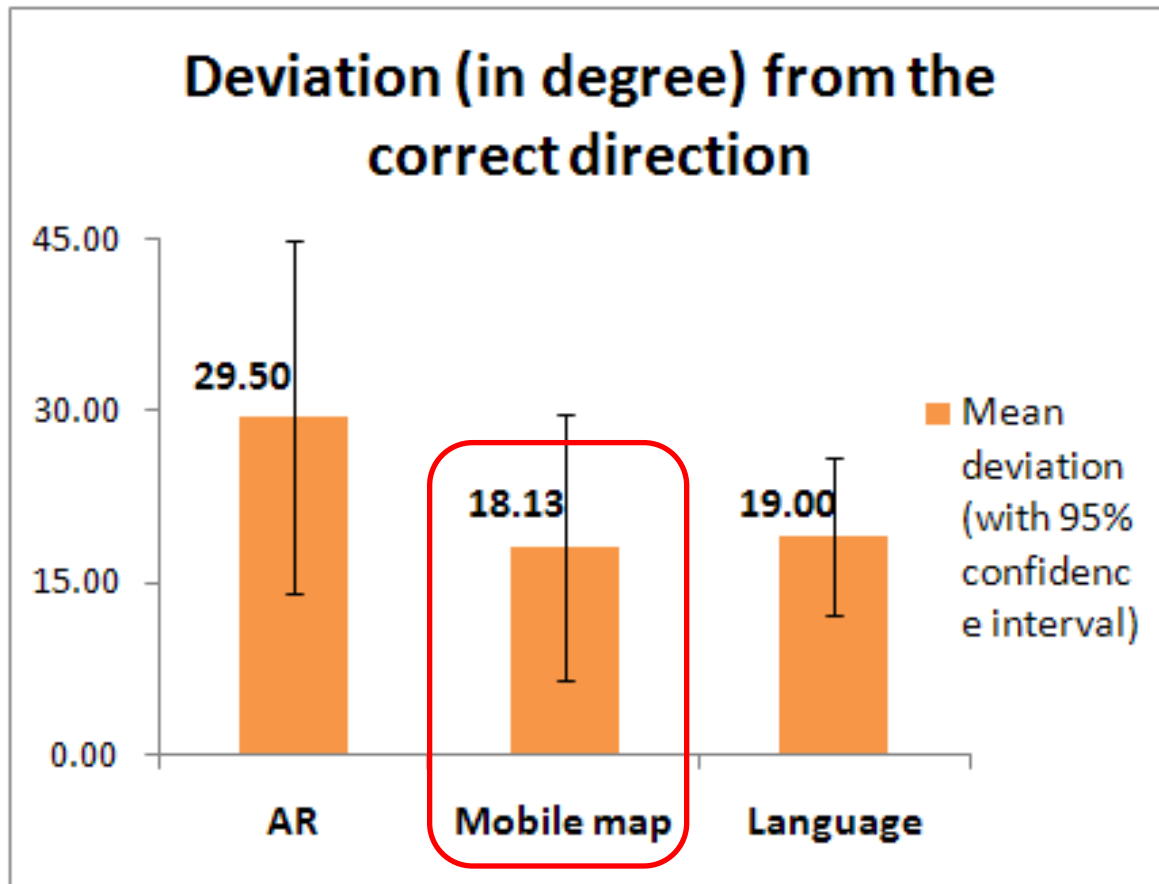


**ANOVA test:**

no significant difference in number of wrong turns across conditions,  $F(2,21) = 1.60$ ,  $p = 0.31$

... in “AR” and “Language”, turns are not presented in a spatial-related overview context

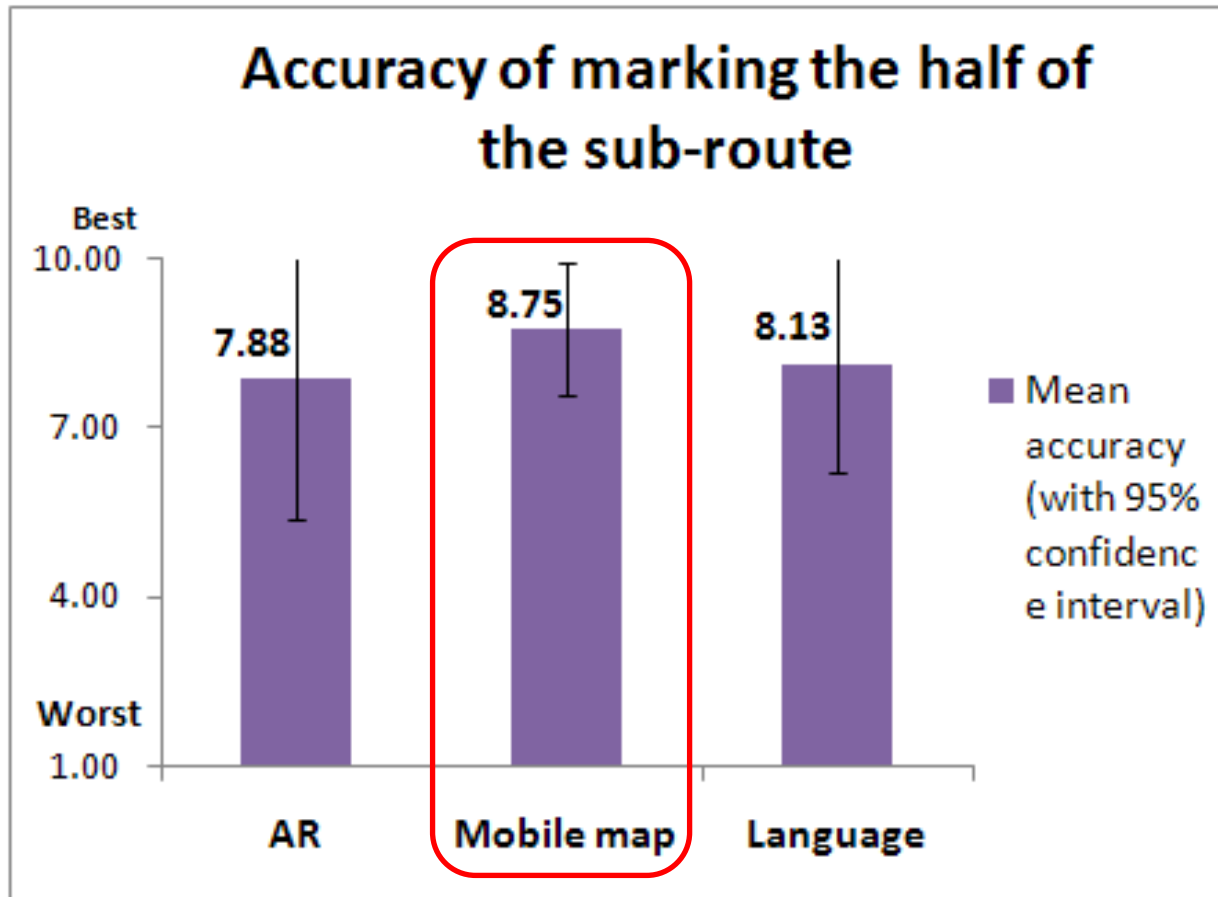
# Results: Sense of Direction



**ANOVA test:**  
no significant difference  
in sense of direction  
across conditions,  
 $F(2,21) = 1.23, p = 0.23$

... “AR” suffers from the poor GPS signal: confusion  
... in “mobile map” condition, subjects seldom used the  
zooming function

# Results: Sense of Distance



**ANOVA test:**  
no significant difference in sense of distance across conditions,  
 $F(2,21) = 0.3$ ,  $p = 0.74$

... For all three conditions, the knowledge on sense of distance is mainly gained from sensual perception of real world (not from presentation forms)

# Summary of the Results

Compared to “language” and “AR”, using “mobile map” leads to **better** spatial knowledge acquisition, reflecting by ...

- ... more accuracy in pointing the start point
- ... more accuracy in sketching turns
- ... more accuracy in marking the half of the route
- ... however, no significant differences

No clear results on sketched landmarks ...

- ... landmarks are not explicitly highlighted in “mobile map” and “AR”

# Work in Progress: 2<sup>nd</sup> Iteration

- Improving the navigation systems: mobile map, language, and AR
- Refining the methodology
  - ... differentiate three kinds of spatial knowledge (landmark, route and survey knowledge)

# Open Research Questions

Do users care about spatial knowledge acquisition?

... If yes, how can we design a navigation system which not only efficiently guides users from A to B, but also enables them to acquire spatial knowledge during navigation?



# Thank you!

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